# Principal Component Analysis 

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$25^{\text {th }}$ July 2020

## Curse of dimensionality

- Several challenges in dealing with high dimensional data
- Model performance reduces
- In several cases, \#samples < \#dimensions
- All distances become similar in high dimensions
- There can be noisy features


Accuracy decreases as the dimensionality increases. 2 class classification accuracy of SVM classifier applied on 200 samples data ( $80 \%$ training) as the dimensionality increases. Classes are Gaussian with means at 0 and 1 and identity covariance.

## Dimensionality reduction

- Solution: Remove some features using domain knowledge
- Might lose out on useful information
- Another option: Remove dimension that carries lesser information
- Different dimensions have different amount of information
- Maybe we can remove the dimension which has lesser information?
- These "dimensions" are inherent in the data and may not always align with the dimensions represented by the features
- That way, number of dimensions is reduced while minimizing the loss of information


## Coordinates recap

- The vector (point) $a$ is in a 2-D space: $a=[1,1]^{T}$
- Unit vector corresponding to $\mathbf{x}_{\mathbf{1}}$ axis: $\mathbf{x}_{\mathbf{1}}=[1,0]^{T}$
- Unit vector corresponding to $\mathbf{x}_{2}$ axis: $\mathbf{x}_{\mathbf{2}}=[0,1]^{T}$
- Any point in the space can be given as weighted sum of vectors $\mathbf{x}_{1}$ and $\mathbf{x}_{2}$


## There can be other axes too...



- Point $a$ has an equivalent representation for choice of axes ( $\mathbf{x}_{1}^{\prime}, \mathbf{x}_{2}^{\prime}$ ) and ( $\mathbf{x}_{1}^{\prime \prime}, \mathbf{x}_{2}^{\prime \prime}$ )
- The other axes are obtained by rotating ( $\mathbf{x}_{1}, \mathbf{x}_{2}$ ) around the origin
- All other such axes-pairs obtained by rotation ( $\mathbf{x}_{1}, \mathbf{x}_{2}$ ) are valid axes


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- All other such axes-pairs obtained by rotation ( $\mathbf{x}_{\mathbf{1}}, \mathbf{x}_{2}$ ) are valid axes
- The rotated pairs are also valid 'dimensions' of the data

Multiple points with rotated axes


All the points can be represented in the 3 axes pairs

| Point | $\mathbf{x}_{\mathbf{1}}$ | $\mathbf{x}_{\mathbf{2}}$ |
| :---: | :---: | :---: |
| $a$ | 1 | 1 |
| $b$ | 2 | 2 |
| $c$ | 3 | 3 |


| Point | $\mathbf{x}_{\mathbf{1}}^{\prime}$ | $\mathbf{x}_{\mathbf{2}}^{\prime}$ |
| :---: | :---: | :---: |
| $a$ | $\frac{\sqrt{3}+1}{2}$ | $\frac{\sqrt{3}-1}{2}$ |
| $b$ | $\sqrt{3}+1$ | 2 |
| $c$ | $\frac{3 \sqrt{3}+3}{2}$ | $\frac{3 \sqrt{3}-3}{2}$ |


| Point | $\mathbf{x}_{\mathbf{1}}^{\prime \prime}$ | $\mathbf{x}_{\mathbf{2}}^{\prime \prime}$ |
| :---: | :---: | :---: |
| $a$ | $\sqrt{2}$ | 0 |
| $b$ | $2 \sqrt{2}$ | 0 |
| $c$ | $3 \sqrt{2}$ | 0 |

## Multiple points with rotated axes

- If $\left(\mathbf{x}_{1}^{\prime \prime}, \mathbf{x}_{2}^{\prime \prime}\right)$ is the choice of axes, then the data is essentially one dimensional
- The data here is one dimensional
- For any given set of points, if we can find a axes pair such that few coordinates are needed, then we have achieved dimensionality reduction


| Point | $\mathbf{x}_{\mathbf{1}}$ | $\mathbf{x}_{\mathbf{2}}$ |
| :---: | :---: | :---: |
| $a$ | 1 | 1 |
| $b$ | 2 | 2 |
| $c$ | 3 | 3 |


| Point | $\mathbf{x}_{\mathbf{1}}^{\prime}$ | $\mathbf{x}_{\mathbf{2}}^{\prime}$ |
| :---: | :---: | :---: |
| $a$ | $\frac{\sqrt{3}+1}{2}$ | $\frac{\sqrt{3}-1}{2}$ |
| $b$ | $\sqrt{3}+1$ | 2 |
| $c$ | $\frac{3 \sqrt{3}+3}{2}$ | $\frac{3 \sqrt{3}-3}{2}$ |


| Point | $\mathbf{x}_{\mathbf{1}}^{\prime \prime}$ | $\mathbf{x}_{\mathbf{2}}^{\prime \prime}$ |
| :---: | :---: | :---: |
| $a$ | $\sqrt{2}$ | 0 |
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| $c$ | $3 \sqrt{2}$ | 0 |

## What is the dimensionality of the data here?



The data shown here is one dimensional

## What is the dimensionality of the data here?



The data shown here is two dimensional

## What is the dimensionality of the data here?



The data shown here is three dimensional

## Criteria for selecting axes

Consider the case that after transformation (projection), the first axis is kept. Which of the following is the best axes?


| Point | $\mathbf{x}_{\mathbf{1}}$ | $\mathbf{x}_{\mathbf{2}}$ |
| :---: | :---: | :---: |
| $a$ | 1 | 1 |
| $b$ | 2 | 2 |
| $c$ | 3 | 3 |


| Point | $\mathbf{x}_{\mathbf{1}}^{\prime}$ | $\mathbf{x}_{\mathbf{2}}^{\prime}$ |
| :---: | :---: | :---: |
| $a$ | $\sqrt{2}$ | 0 |
| $b$ | $2 \sqrt{2}$ | 0 |
| $c$ | $3 \sqrt{2}$ | 0 |


| Point | $\mathbf{x}_{\mathbf{1}}^{\prime \prime}$ | $\mathbf{x}_{\mathbf{2}}^{\prime \prime}$ |
| :---: | :---: | :---: |
| $a$ | 0 | $-\sqrt{2}$ |
| $b$ | 0 | $-2 \sqrt{2}$ |
| $c$ | 0 | $-3 \sqrt{2}$ |

## Criteria for selecting axes

- The second scenario is the best because the entire "spread" of the data is conserved; spread is the variance
- Variance can also be thought of as the information in the data


| Point | $\mathbf{x}_{\mathbf{1}}$ |
| :---: | :---: |
| $a$ | 1 |
| $b$ | 2 |
| $c$ | 3 |


| Point | $\mathbf{x}_{\mathbf{1}}^{\prime}$ |
| :---: | :---: |
| $a$ | $\sqrt{2}$ |
| $b$ | $2 \sqrt{2}$ |
| $c$ | $3 \sqrt{2}$ |


| Point | $\mathbf{x}_{\mathbf{1}}^{\prime \prime}$ |
| :---: | :---: |
| $a$ | 0 |
| $b$ | 0 |
| $c$ | 0 |

## Data may not be collinear

- Goal is to rotate the axes and then keep data of only one axis
- Which orientation of axes pairs to choose and which of the two axis to keep?
- Criteria of maximizing variance can be applied here too
- We want to minimize the information loss



## Optimization formulation

- Let the data be $x_{1}, x_{2}, \ldots, x_{N}$ where $x_{i}=\left[x_{i 1}, x_{i 2}\right]^{T}$
- Let $\mathbf{u}_{1}$ be the unit vector corresponding to the axis that is retained after dimensionality reduction
- $x_{i}^{\prime}$ is the projection of $x_{i}$ on $\mathbf{u}_{\mathbf{1}}$

$$
x_{i}^{\prime}=\mathbf{u}_{1}^{T} x_{i}
$$

- Variance: $\frac{1}{N} \sum_{i=1}^{N}\left(x_{i}^{\prime}-\overline{x^{\prime}}\right)^{2}$



## Optimization formulation

- Variance: $\frac{1}{N} \sum_{i=1}^{N}\left(x_{i}^{\prime}-\overline{x^{\prime}}\right)^{2}$
- Substituting:

$$
x_{i}^{\prime}=\mathbf{u}_{1}^{T} x_{i}
$$

we get,

$$
\frac{1}{N} \sum_{i=1}^{N}\left(\mathbf{u}_{1}^{T} x_{i}-\mathbf{u}_{\mathbf{1}}^{T} \bar{x}\right)^{2}
$$

$$
=\mathbf{u}_{\mathbf{1}}^{T} \mathrm{~S} \mathbf{u}_{\mathbf{1}}
$$

where,


## Optimization problem

- Variance: $\mathbf{u}_{\mathbf{1}}^{T} \mathbf{S} \mathbf{u}_{\mathbf{1}}$
- To find best $\mathbf{u}_{1}$, maximize the variance

$$
\begin{aligned}
& \max _{\mathbf{u}_{\mathbf{1}}} \mathbf{u}_{\mathbf{1}}^{T} \mathrm{~S} \mathbf{u}_{\mathbf{1}} \\
& \text { s.t. } \mathbf{u}_{1}^{T} \mathbf{u}_{\mathbf{1}}=1
\end{aligned}
$$



## Solution to the optimization problem

- To find best $\mathbf{u}_{1}$, maximize the variance

$$
\begin{aligned}
& \max _{\mathbf{u}_{\mathbf{1}}} \mathbf{u}_{\mathbf{1}}^{T} \mathrm{~S} \mathbf{u}_{\mathbf{1}} \\
& \text { s.t. } \mathbf{u}_{\mathbf{1}}^{T} \mathbf{u}_{\mathbf{1}}=1
\end{aligned}
$$

- Solution: $\mathbf{u}_{\mathbf{1}}$ is the first eigenvector of covariance matrix S, i.e.,

$$
S \mathbf{u}_{1}=\lambda_{1} \mathbf{u}_{1}
$$

where $\lambda_{1}$ is the largest eigenvalue of $S$.

- Variance explained by $\mathbf{u}_{1}$ is $\lambda_{1}$



## To retain more than one dimension...

- For data with $d$ dimensions, we might be interested in the $k<d$ axes $\mathbf{u}_{1}, \mathbf{u}_{2}, \ldots, \mathbf{u}_{\mathbf{k}}$, such that the variance of the projected data is maximized
- A similar optimization problem as above can be setup
- Solution is to choose the axes as the first $k$ eigenvectors of $S$, i.e.,

$$
S \mathbf{u}_{\mathbf{j}}=\lambda_{j} \mathbf{u}_{\mathbf{j}} \quad \text { for } j=1, \ldots, k
$$

- Variance explained by $\mathbf{u}_{\mathbf{j}}$ is $\lambda_{j}$; $\mathbf{u}_{\mathbf{j}}$ is the $\mathrm{j}^{\text {th }}$ principal component
- Variance explained by $\mathbf{u}_{1}, \ldots, \mathbf{u}_{\mathbf{k}}$ is $\lambda_{1}+\lambda_{2}+\cdots+\lambda_{k}$
- Total variance is the original data is sum of all eigenvalues $\lambda_{1}+\lambda_{2}+\cdots+\lambda_{d}$
- In practice, $k$ might not be known to begin with, so all eigenvectors and eigenvalues are computed and then then $k$ is decided


## PCA applied to Iris data

- 150 samples with 3 classes of flowers
- 4 dimensions: petal width, petal length, sepal width, sepal length
- \% variance explained by $j^{\text {th }}$ component $=\frac{\lambda_{j}}{\lambda_{1}+\cdots+\lambda_{d}}$
- $92 \%$ of the variance is explained by first principal component (PC)


Iris Versicolor


Iris Setosa


## Visualization of data in PC space


$k=1$; projection on only the first PC ( $92 \%$ variance)

$k=2$; projection on the first two PCs (98\% variance)

## PCA applied to Diabetes data

- 442 diabetic individuals with information on one-year progression of disease
- 8 dimensions: age, body mass index, average blood pressure, and five blood serum measurements
- $41 \%$ of the variance is explained by first principal component (PC)
- Number of components to retain
- Rule of thumb: 80\%

- Elbow


## Visualization of data in PC space


$k=2$; projection on the first two
PCs (58\% variance)

## Interpreting the PCs



- PC1 is mainly driven by petal length
- High value of PC1 suggests flower has long petal
- Note that the projected data has a zero mean
- PC2 is mainly driven by septal width and length
- High value of PC2 suggests that a flower has large sepals


## Relation of eigenvalues to covariance matrix

- Why was the \% variance explained by first component so different in the two datasets?

- Correlation matrix (related to covariance matrix) for the two datasets

- More high correlation between variables in Iris dataset


## Relation between covariance matrix and eigenvalues



Cov. mat:
$\left[\begin{array}{cc}1 & 0 \\ 0 & 1\end{array}\right] \quad \begin{gathered}\text { Tot. var. }=2 \\ \lambda_{1}=1\end{gathered}$


Cov. mat:
$\left[\begin{array}{cc}1 & 0.8 \\ 0.8 & 1\end{array}\right] \begin{aligned} & \text { Tot. var. }=2 \\ & \lambda_{1}=1.8\end{aligned}$

Cov. mat:

$$
\left[\begin{array}{cc}
1 & 0.95 \\
0.95 & 1
\end{array}\right] \begin{aligned}
& \text { Tot. var. }=2 \\
& \lambda_{1}=1.95
\end{aligned}
$$

- As the covariance increases, first eigenvalues increases
- Consequently, \% variance explained by first PC will also increase


## Scale of the features affects PCA




| Cov. mat: | Tot. var. $=10.1$ | PC1 | PC2 | Cov. mat: | Tot. var. $=2$ | PC1 | PC2 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\left[\begin{array}{ll}10 & 0.5 \\ 0.5 & 0.1\end{array}\right]$ | $\lambda_{1}=10.02$ | $\left[\begin{array}{c}0.99 \\ 0.06\end{array}\right]\left[\begin{array}{c}-0.06 \\ 0.99\end{array}\right]$ | $\left[\begin{array}{cc}1 & 0.5 \\ 0.5 & 1\end{array}\right]$ | $\lambda_{1}=1.5$ | $\left[\begin{array}{c}0.66 \\ 0.75\end{array}\right]\left[\begin{array}{c}-0.75 \\ 0.66\end{array}\right]$ |  |  |

- In the first case, $>90 \%$ of the variance is explained by PC1 but PC1 is mainly driven by the first feature (since it has a relatively larger variance)
- In the second case, $75 \%$ of the variance is explained by PC1 and it has similar contribution of both the features
- The correlation between the two features is the same in both cases


## Scale of features affects PCA

- Features with larger variance dominate PCs and may result in loss of useful information
- Example: Analysing COVID-19 data with features of age (range 20-80), blood oxygen level (range 90-98), body temperature (range 97-104)
- Most important features relation to severity might be oxygen level but it has a smaller variance compared to others
- Solution: Standardizing features (making them zero mean and unit variance) before PCA computations
- Equivalent to using correlation matrix for analysis

Covariance matrix $=\left[\begin{array}{cc}\sigma_{1}^{2} & \rho \sigma_{1} \sigma_{2} \\ \rho \sigma_{1} \sigma_{2} & \sigma_{2}^{2}\end{array}\right] \longrightarrow$ Correlation matrix $=\left[\begin{array}{ll}1 & \rho \\ \rho & 1\end{array}\right]$

- For a given application of PCA, should correlation matrix be used, or covariance matrix be used?
- Depends on the application


## Loss of information relevant for classification










- Inherent assumption is that variance between clusters/classes would be more than variance within clusters/classes
- Removing low variance PC might result in loss of information relevant to classification


## Good references for PCA

- Bishop book on pattern recognition
- http://www.cse.psu.edu/~rtc12/CSE586Spring2010/lectures/pcaLect ureShort.pdf
- https://www.cs.cmu.edu/~mgormley/courses/10701-f16/slides/lecture14-pca.pdf

Miscellaneous

## Which method to use?

Depends on the dataset!

|  | Logistic Regression | SVM | Random Forest |
| :--- | :--- | :--- | :--- |
| Decision Boundary | Linear | Non-linear (w/ kernel) | Non-linear |
| Provides probability of class | Yes | No; but there are ways <br> of estimating | No; but there are ways <br> of estimating |
| Interpretability | Yes | Yes | Lesser than decision <br> trees and other methods |
| Handles large dimensionality | No | Yes | Yes |
| Handles large number of samples | Yes | Slow for >10k samples | Yes |
| Handles categorical features | Yes if few | No | Yes |
| Features with different scales | Yes | No ("distance" may not <br> be meaningful) | Yes |
| Handles missing data | No | No | Yes |

Visual resource: https://scikit-learn.org/stable/tutorial/machine learning map/index.html

## Neural Networks

Learns non-linear decision boundary by combining input data non-linearly
Hidden layers


Advantages

- Non-linear decision boundary
- Learns features from the data

Challenges

- Large amounts of training data
- Training is computationally heavy
- Low interpretability

Questions?

